## MOTIVATION FOR EIGENVALUES AND EIGENVECTORS

1. An example of a system of linear, first-order differential equations.

$$\frac{dv}{dt} = v(t) - w(t) \qquad \qquad v(0) = 40$$

$$\frac{dw}{dt} = 2v(t) - 4w(t)$$
  $w(0) = 10$ 

**2.** A solution:  $v(t) = 90e^{2t} - 50e^{3t}$ ,  $w(t) = -90e^{2t} + 100e^{3t}$ .

## Null Spaces

3. Let A be an  $m \times n$  matrix, then the **null space of** A is

4. Example 1: 
$$A = \begin{bmatrix} 1 & 2 \\ 10 & 20 \end{bmatrix}$$

5. Example 2: 
$$B = \begin{bmatrix} 1 & 0 & 1 \\ 5 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix}$$

- 6. Show/prove/give an argument for each of the statements below.
  - (a) For every matrix A,  $N(A) \neq \emptyset$ .
  - (b) If A is invertible, then N(A) contains only the zero vector.
  - (c) If the vector x is in N(A), then for any number c, cx is in N(A).

(d) If both of the vectors x and y are in N(A), then the vector x + y is also in N(A).

(e) If x is in N(A) and the vector z is not in N(A), then x and z are linearly independent.

(f) If the vector *a* is in N(A) and *c* is a solution to Ax = b, then c + a is also a solution to Ax = b.

(g) If both of the vectors  $c_1$  and  $c_2$  are solutions to Ax = b, then there is a vector a in N(A) such that  $c_2 = c_1 + a$ .

## 7. Main Principles