Null Spaces def: A is an mxn matrix. The null space of A, denoted N(A), is the set of all n-vectors, x, such that Ax=O.  $\begin{bmatrix} E_{X1} \\ A = \begin{bmatrix} 1 & 2 \\ 10 & 20 \end{bmatrix} \quad X = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \text{ is in } N(A) \text{ and}$  $y = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is not in N(A) be cause  $A \times = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ and } A y = \begin{bmatrix} 3 \\ 3 0 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ Ex2 Determine the null space of  $A = \begin{bmatrix} 1 & 0 & 1 \\ 5 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix}$ We need to find all X where Ax=0. To solve:  $\begin{bmatrix} A : 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 : 0 \\ 5 & 4 & 9 : 0 \\ 2 & 4 & 6 : 0 \end{bmatrix} \xrightarrow{\text{tref}} \begin{bmatrix} 1 & 0 & 1 : 0 \\ 0 & 1 & 1 : 0 \\ 0 & 0 & 0 : 0 \end{bmatrix}$ \* Why didn't we solve this using A-1?

$$\begin{aligned} x_{1} & x_{2} x_{3} \\ \begin{bmatrix} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \longrightarrow x_{1} + x_{3} = 0 \qquad x_{1} = -x_{3} \\ x_{2} + x_{3} = 0 \qquad x_{2} = -x_{3} \end{aligned}$$

$$\begin{aligned} x = \begin{bmatrix} -x_{3} \\ -x_{3} \\ -x_{3} \end{bmatrix} = \begin{bmatrix} a \\ -a \end{bmatrix} \qquad \text{Ansaer: } \mathcal{N}(A) = \begin{cases} a \\ -a \end{bmatrix} : a \in \mathbb{R} \end{cases}$$

$$\begin{aligned} guh \\ eherk: & \begin{bmatrix} 1 & 0 & 1 \\ 5 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix} \begin{bmatrix} 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 2 - 2 \\ 10 + 8 - 18 \\ 4 + 8 - 12 \end{bmatrix} \mathcal{N} \begin{bmatrix} 1 & 0 & 1 \\ 5 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ -a \end{bmatrix} \end{aligned}$$

$$\begin{aligned} Example 1 \qquad \text{Revisiked} \end{aligned}$$

$$\begin{aligned} Find \quad \mathcal{N}(A) \text{ for the matrix in Example 1.} \\ \text{Answer:} \qquad \mathcal{N}(A) = \begin{cases} \begin{bmatrix} 2a \\ -a \end{bmatrix} : a \in \mathbb{R}^{2} \\ 3o \end{bmatrix} \end{aligned}$$

$$\begin{aligned} Find \quad all \text{ solutions to } A \times = \begin{bmatrix} 3 \\ 3o \end{bmatrix} \\ \begin{bmatrix} 1 & 2 & 3 \\ 10 & 20 & 30 \end{bmatrix} \xrightarrow{\text{ref}} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{array}{c} x_{1} + 2x_{2} = 3 \\ x_{1} = 3 - 2x_{2} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 3 - 2x_{2} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix} + \begin{bmatrix} -2x_{2} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix} + \begin{bmatrix} 2a \\ -a \end{bmatrix} : a \in \mathbb{R} \end{aligned}$$

## Show $\mathbb{O} N(A) \neq \emptyset$

(1.5) Find a 3×3 matrix A such that  $N(A) = \left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}.$ 

- (2) If x is in N(A), then cx is in N(A) for any number c.
- (3) If x and y are in N(A), then x+y is in N(A).
- (4) If x is in N(A) and z is not in N(A), then x and z are linearly independent.

5) If x is a solution to Ax=0 and Z is a solution to Ax=b, then Z+X is a solution to Ax=b.

() If Z, and Zz are solutions to Ax=b,

then there is an x in N(A) so that  $Z_2 = Z_1 + X$ 

Big Principles

(1.5) If A is invertible, then N(A) = {o}. (2+3) N(A) is a subspace. No linear combination of vectors in N(A) can fall outside of N(A)

(5+6) The set of all solutions to Ax=b can be described by finding one particular solution to Ax=b, say xp, and adding it to the rectors in N(A).