

Mon 21 October  
Weather Day!

- Hmwk 7 due Wed
- Quiz 6 on Fri

8.4.2

1	4	7
2	5	8
3	6	9

1
2
3
4
5
6
7
8
9

= x

"turn upside down"

9x9

$$A x = y$$

↑

↑

q-vector q-vector

reflection

rotation

3	6	9
2	5	8
1	4	7

9	6	3
8	5	2
7	4	1

7	8	9
4	5	6
1	2	3

# QR-Factorization

- $a_1, a_2, \dots, a_n$   $m$ -vectors, orthonormal

This means

- $\|a_i\| = 1$  for all  $i$

- for  $i \neq j$ ,  $a_i \perp a_j \equiv$

$$a_i^T a_j = 0$$

- Construct:  $A = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & a_3 & \dots & a_n \\ | & | & & | \end{bmatrix}$

$$= [a_1 \ a_2 \ \dots \ a_n]$$

an  $m \times n$  matrix.

~~$A = AA$   
 $(m \times n) (m \times n)$   
need  $m = n$~~

- $A^T A = \begin{bmatrix} \text{---} & a_1 & \text{---} \\ \text{---} & a_2 & \text{---} \\ \text{---} & a_3 & \text{---} \\ \text{---} & a_n & \text{---} \end{bmatrix} \begin{bmatrix} | & | & | & | \\ a_1 & a_2 & a_3 & \dots & a_n \\ | & | & | & | \end{bmatrix}$

$$\begin{array}{c}
 \begin{array}{|c}
 \hline a_1^T \\
 \hline a_2^T \\
 \hline a_3^T \\
 \hline \vdots \\
 \hline a_n^T \\
 \hline
 \end{array}
 \cdot
 \begin{array}{|c}
 \hline | \\
 \hline a_1 \\
 \hline | \\
 \hline a_2 \\
 \hline | \\
 \hline a_3 \\
 \hline \vdots \\
 \hline | \\
 \hline a_n \\
 \hline
 \end{array}
 =
 \begin{array}{|c}
 \hline 1 \\
 \hline 0 \\
 \hline 0 \\
 \hline \vdots \\
 \hline 0 \\
 \hline
 \end{array}
 \begin{array}{|c}
 \hline 0 \\
 \hline 1 \\
 \hline 0 \\
 \hline \vdots \\
 \hline 0 \\
 \hline
 \end{array}
 \begin{array}{|c}
 \hline 0 \dots 0 \\
 \hline 0 \dots 0 \\
 \hline 1 \dots 0 \\
 \hline \vdots \\
 \hline 0 \dots 0 \\
 \hline
 \end{array}
 \end{array}$$

$A^T \quad \cdot \quad A$   
 $(n \times m) \quad (m \times n)$

$(n \times n)$   
 the identity matrix

$$\begin{aligned}
 0 &= a_1^T a_2 \quad \text{b/c } a_1 \perp a_2 \\
 1 &= a_1^T a_1 = \|a_1\|^2 = 1^2
 \end{aligned}$$

• Observation: If  $A$  has  $n$  o.n. columns, then  $A^T A = I_n$

$$I_n B = B$$

$$(A^T A)x = A^T b$$

$$I_n \cdot x = A^T b$$

$$x = A^T b \quad \checkmark$$

$$\frac{5x}{5} = \frac{3}{5}$$

$$x = \frac{3}{5}$$

$$\left(\frac{1}{5}\right) 5x = \left(\frac{1}{5}\right) 3$$

$$(5^{-1} \cdot 5)x = 5^{-1} \cdot 3$$

$$1 \cdot x = 5^{-1} \cdot 3$$

def:  $a_1, a_2, \dots, a_n$   $n$ -vector and orthonormal

then  $A = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & \dots & a_n \\ | & | & & | \end{bmatrix}$  is called

orthogonal.

Ex

Ex orthogonal matrix  $\begin{bmatrix} | & | & & | \\ e_1 & e_2 & \dots & e_n \\ | & | & & | \end{bmatrix}$

$$\begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ a_1 & a_2 \end{bmatrix}$$

$2 \times 2$

$I_n$

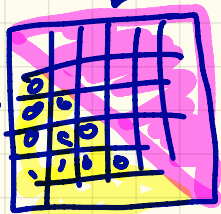
Suppose  $A$  is  $n \times n$  matrix and its columns are linearly independent.

Then there exist matrices  $Q, R$  so that

①  $QR = A$

②  $Q$  is orthogonal ( $n \times n$ )  
and

③  $R$  is upper triangular



# QR factorization

Suppose  $A$  is an  $n \times n$  matrix with columns  $a_1, a_2, \dots, a_n$  linearly independent.

Then there exist  $n \times n$  matrices  $Q$  and  $R$  such that  $A = QR$

•  $Q$  is orthogonal  
and

•  $R$  is upper triangular.

Ex  $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$

$$= \frac{1}{2} - \frac{1}{6} + \frac{2 \cdot 2}{3 \cdot 2} = \frac{3 - 1 + 4}{6} = \frac{6}{6}$$

Vectors  $a_1 = (1, 1, 0)$ ,  $a_2 = (1, 0, 1)$ ,  $a_3 = (0, 1, 1)$

are linearly independent.

$$Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} \sqrt{2} & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{3}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ 0 & 0 & \frac{2}{\sqrt{3}} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} = A$$

↑ normal ✓  
↑ orthog ✓

↑ upper  $\Delta$

$QR = A$  ✓

$$\begin{aligned} 2x + 3y &= 5 \\ x - 2y &= 7 \end{aligned}$$

$$\begin{bmatrix} 2 & 3 & 5 \\ 1 & -2 & 7 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & a_1 \\ 0 & 1 & a_2 \end{bmatrix}$$

$$x = a_1$$

$$y = a_2$$

✓

$$Ax = b$$

$$\begin{bmatrix} I_n & Q^T \\ Q & R \end{bmatrix} x = \begin{bmatrix} Q^T \\ Q \end{bmatrix} b$$

$$Rx = Q^T b$$

$c_1$   
 $c_2$   
 $\vdots$   
 $c_n$

$$\begin{aligned} a_{n2}x_{n2} + a_{n1}x_{n1} + a_{nn}x_n &= c_{n2} \\ a_{n1}x_{n1} + a_{nn}x_n &= c_{n1} \\ a_{nn}x_n &= c_n \end{aligned}$$

↑ back substitution