

Name: Solutions

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There are 10 points possible on this quiz. You may use technology but you must demonstrate what you are using technology for.

Questions below concern bases of \mathbb{R}^2

$$\mathcal{E}_2 = \left\langle \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\rangle, \quad B = \left\langle \begin{pmatrix} 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right\rangle, \quad D = \left\langle \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\rangle.$$

1. (2 points) Find **directly** the representation of the vector \vec{v} with respect to \mathcal{E}_2 assuming $Rep_B(\vec{v}) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}_B$.

$$\begin{pmatrix} 2 \\ 3 \end{pmatrix}_B = 2 \begin{pmatrix} 0 \\ -1 \end{pmatrix} + 3 \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -2 \end{pmatrix} + \begin{pmatrix} 6 \\ 3 \end{pmatrix} = \begin{pmatrix} 6 \\ 1 \end{pmatrix}$$

2. (2 points) Find the matrix $A_1 = Rep_{B, \mathcal{E}_2}(id)$.

$$A_1 = \begin{bmatrix} 0 & 2 \\ -1 & 1 \end{bmatrix}$$

$$A_1 \begin{pmatrix} \vec{v} \end{pmatrix}_B = \begin{bmatrix} 0 & 2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix}_B = \begin{pmatrix} 6 \\ 1 \end{pmatrix} \checkmark$$

3. (1 point) Use matrix A_1 to find $Rep_{\mathcal{E}_2}(\vec{v})$.

4. (5 points) Suppose that, with respect to \mathcal{E}_2 for both domain and codomain, the transformation $h: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is represented by the matrix $H = \begin{pmatrix} 6 & -8 \\ 2 & -8 \end{pmatrix}$. Use change of basis matrices to represent h with respect to the bases

$$B = \left\langle \begin{pmatrix} 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right\rangle \quad \text{and} \quad D = \left\langle \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\rangle.$$

where B is the basis for the domain and D is the basis for the range.

$$M_1 = \begin{bmatrix} 0 & 2 \\ -1 & 1 \end{bmatrix} \quad \text{changes } B \text{ to } \mathcal{E}_2.$$

Need M_3 changes \mathcal{E}_2 to D .

$$\begin{bmatrix} 1 & -1 & | & 1 & 0 \\ 1 & 1 & | & 0 & 1 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & | & 1/2 & 1/2 \\ 0 & 1 & | & -1/2 & 1/2 \end{bmatrix}, \quad M_3 = \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix}$$

$D \leftarrow \mathcal{E}_2$

$$\begin{aligned} \text{Rep}_{B,D}(h) &= M_3 \cdot H \cdot M_1 = \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 6 & -8 \\ 2 & -8 \end{bmatrix} \begin{bmatrix} 0 & 2 \\ -1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 8 & 0 \\ 0 & -4 \end{bmatrix} \end{aligned}$$