

SECTION 2.3.3: VECTOR SPACES AND LINEAR SYSTEMS

1. **definition** The *row space* of a matrix is *the span of the rows of A*

The *row rank* is *the dimension of the row space*

2. Lemma 3.4: Let  $A'$  be the reduced row echelon form of matrix  $A$ . The rows of  $A'$  are

a *basis* for the row space of  $A$ .

Why? ① *row space*  $(A) = \text{row space}(A')$  since *they are row equivalent.*  
 ② *nonzero rows of  $A'$  are linearly independent.*

3. **definition** The *column space* of a matrix is *the span of columns of A*

The *column rank* is *the dimension of column space of A.*

4. **definition** The *transpose* of a matrix is *the matrix obtained by switching rows & columns.*

*col space A = row space  $A^T$*

5. Lemma 3.10: Row operations do not change *Column rank.*

6. Theorem: For any matrix, what is the relationship between row rank and column rank of matrices?

*They are equal! row rank  $(A) = \text{col. rank}(A)$*

7. **definition** The rank of a matrix is *col rank or row rank.*

8. Theorem: For linear systems with  $n$  unknowns and with coefficient matrix  $A$  the following statements are equivalent.

- $A$  has rank  $r$
- $\text{rref}(A)$  has  $r$  leading 1's
- $\text{dim}$  of solution space of  $[A; \begin{smallmatrix} 0 \\ \vdots \\ 0 \end{smallmatrix}]$  is  $n-r$ .  
 (i.e.  $\text{rref}(A)$  has  $n-r$  columns that do NOT have leading 1's)

9. Corollary: For the  $n \times n$  matrix  $A$ , the following are equivalent.

- $A$  has rank  $n$
- $A$  is nonsingular
- rows are linearly independent
- columns are linearly independent
- Any SOLE  $([A; \vec{b}])$  with  $A$  as a coefficient matrix has a unique solution.