SECTION 3.2.1 HOMOMORPHISMS/LINEAR MAPS

- 1. **Review** For vector spaces *V* and *W*, the function $f : V \to W$ is called an *isomorphism* if
- 2. **Review** For vector spaces *V* and *W*, the function $f : V \to W$ is called a *homomorphism* or *linear map* if
- 3. Examples:

(a)
$$f: \mathcal{P}_2 \to \mathbb{R}^2$$
 defined as $f(ax^2 + bx + c) = \begin{pmatrix} a \\ b + c \end{pmatrix}$ (or $ax^2 + bx + c \mapsto \begin{pmatrix} a \\ b + c \end{pmatrix}$)

(b) The *projection*
$$\pi : \mathbb{R}^3 \to \mathbb{R}^2$$
 defined by $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} x \\ y \end{pmatrix}$

(c) The zero homomorphism $z: \mathbb{R}^4 \to \mathcal{M}_{2 \times 2}$

4. Lemma 1.6:

5. Theorem 1.9:

6. Consequence of Theorem 1.9: Define a homomorphism h from \mathcal{P}_2 to $\mathcal{M}_{2\times 2}$ by defining h on a basis of \mathcal{P}_2 and demonstrating how h operates on an arbitrary element of \mathcal{P}_2 .

7. Definition 1.12