

SECTION 3.4.4 INVERSES

1. The function $f : V \rightarrow W$, a linear map with matrix representation A , has an inverse if and only if

- f is 1-1 and onto
- f is an isomorphism
- A is nonsingular

2. If the function $f : V \rightarrow W$, a linear map with matrix representation A , has inverse $f^{-1} : W \rightarrow V$ with matrix representation B , then $AB = I_n$ and then $BA = I_n$ (where $n = \dim(V) = \dim(W)$)

Call $B = A^{-1}$.

(So $AA^{-1} = A^{-1}A = I_n$)

So some basic algebra is possible!

Ex] If A is nonsingular, then solve $AC = B$ for matrix C .

$$A^{-1}AC = A^{-1}B$$

$$I_n C = A^{-1}B$$

$$\boxed{C = A^{-1}B}$$

3. If A is a nonsingular $n \times n$ matrix, then $\text{rref}(A) = I_n$.

So $A \xrightarrow[\text{ops}]{\text{row}} I_n$ OR

$$\underbrace{R_k \dots R_2 R_1}_\text{Multiply by elementary reduction matrices.} A = I_n$$

Multiply by elementary reduction matrices.

But now:

$$\underbrace{(R_k \dots R_2 R_1)}_\text{This is } A^{-1} A = I_n$$

So, if we could capture or keep track of row operations we can find A^{-1} .

↓ See next algorithm.

4. Find A^{-1} for $A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 3 \\ 1 & -1 & -2 \end{pmatrix}$.

augmented matrix : $\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 3 & 0 & 1 & 0 \\ 1 & -1 & -2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\text{rref}} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{4} & \frac{1}{4} & \frac{3}{4} \\ 0 & 1 & 0 & \frac{3}{4} & -\frac{5}{4} & -\frac{3}{4} \\ 0 & 0 & 1 & -\frac{1}{4} & \frac{3}{4} & \frac{1}{4} \end{array} \right]$

$A : I_3$

we knew this! captured row ops

So $A^{-1} = \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{3}{4} \\ \frac{3}{4} & -\frac{5}{4} & -\frac{3}{4} \\ -\frac{1}{4} & \frac{3}{4} & \frac{1}{4} \end{bmatrix}$

5. Solve the system of equations

$$\begin{cases} x + 2y + 3z = 8 \\ y + 3z = -4 \\ x - y - 2z = 0 \end{cases}$$

SOLE : $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 3 \\ 1 & -1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 8 \\ -4 \\ 0 \end{bmatrix}$ or $A \vec{x} = \vec{b}$, $\vec{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$, $\vec{b} = \begin{bmatrix} 8 \\ -4 \\ 0 \end{bmatrix}$

So $A^{-1}A\vec{x} = A^{-1}\vec{b}$ or $\vec{x} = A^{-1}\vec{b} = \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{3}{4} \\ \frac{3}{4} & -\frac{5}{4} & -\frac{3}{4} \\ -\frac{1}{4} & \frac{3}{4} & \frac{1}{4} \end{bmatrix} \begin{bmatrix} 8 \\ -4 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \\ -5 \end{bmatrix}$

$1 + 22 - 15 = 23 - 15 = 8 \quad \checkmark$

$11 - 15 = -4 \quad \checkmark$

$1 - 11 - 2(-5) = 11 - 11 = 0 \quad \checkmark$

Most important,
solution algorithm is easy for
all choices of \vec{b} .